



Gradient-Based Discrete Sampling: Algorithms and Applications

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Discrete Data and Models

- Discrete data

Text

- beginning in **december 1934** , training exercises were conducted **for** the tetrarchs and their crews **using** hamilcar gliders .
- beginning in **march 1946** , training exercises were conducted **by** the tetrarchs and their crews **with** hamilcar gliders .
- beginning in **may 1926** , training exercises were conducted **between** the tetrarchs and their crews **using** hamilcar gliders .
- beginning in **late 1942** , training exercises were conducted with the tetrarchs and their crews **onboard** hamilcar gliders .
- beginning in **september 1961** , training exercises were conducted **between** the tetrarchs and their crews **in** hamilcar gliders .

Task: sample from an unnormalized distribution $\pi(\theta) \propto \exp(U(\theta))$

	A	B	C	D	E	F	G
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DNA

11	West	Girl	Tee	1/31/2005	15	13.42	13.29
12	West	Girl	Golf	1/31/2005	15	11.48	10.67

- Discrete models

Binary neural networks

1	1	-1
1	-1	1
-1	1	1

1-bit weight

$\otimes$

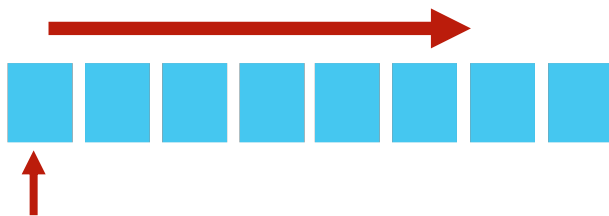
-1	-1	-1	1	1	1	-1	1
1	1	-1	1	1	-1	1	1
1	-1	1	-1	1	1	-1	-1
1	1	1	-1	1	-1	1	1
-1	-1	1	1	1	-1	-1	1
1	-1	-1	1	1	-1	-1	1
1	-1	-1	-1	1	-1	1	1
-1	-1	1	1	1	-1	1	-1

1-bit activation

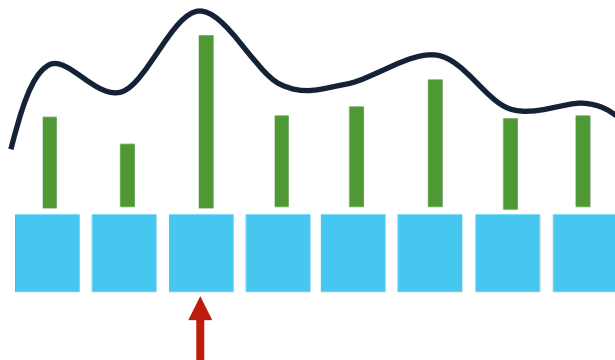
[Qin et al. 2020]

Discrete Samplers

- Gibbs sampling



- Gibbs with Gradients



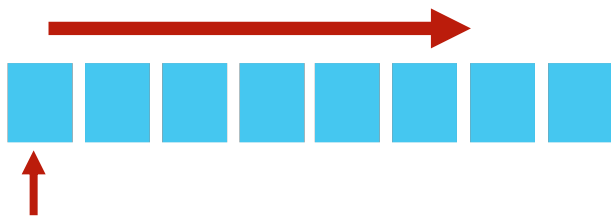
How to obtain gradient in discrete domains?

- Many common discrete unnormalized log-probability are **differentiable** functions

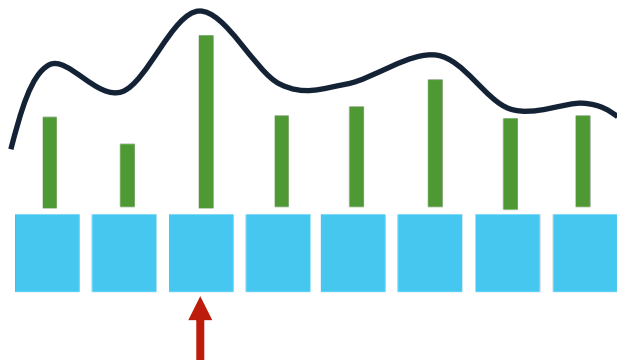
Distribution	$\log p(x) + \log Z$
Categorical	$x^T \theta$
Poisson ¹	$x \log \lambda - \log \Gamma(x + 1)$
HMM	$\sum_{t=1}^T x_{t+1}^T A x_t - \frac{(w^T x - y)^2}{2\sigma^2}$
RBM	$\sum_i \text{softplus}(Wx + b)_i + c^T x$
Ising	$x^T W x + b^T x$
Potts	$\sum_{i=1}^L h_i^T x_i + \sum_{i,j=1}^L x_i^T J_{ij} x_j$
Deep EBM	$f_\theta(x)$

Discrete Samplers

- Gibbs sampling



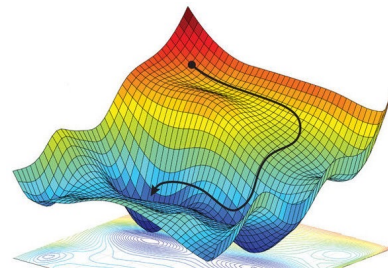
- Gibbs with Gradients



Only update **one** dim:
suffer from **high-dimensional** and highly **correlated** distributions!

Continuous Sampler: Langevin Dynamics

$$\theta' = \theta + \frac{\alpha}{2} \nabla U(\theta) + \sqrt{\alpha} \xi, \quad \xi \sim \mathcal{N}(0, I)$$



- **Gradients** guide the sampler to **efficiently** explore high probability regions
- **Cheaply** update **all** coordinates in parallel in a single step

What is the analog of Langevin dynamics in discrete domains?

Our Method: Discrete Langevin Proposal

$$q(\theta'|\theta) = \frac{\exp\left(-\frac{1}{2\alpha} \left\|\theta' - \theta - \frac{\alpha}{2} \nabla U(\theta)\right\|_2^2\right)}{Z_{\Theta}(\theta)}$$

- Langevin proposal is applicable to **any** kind of spaces
 - When $\Theta = \mathbb{R}^d$, recover the Gaussian proposal
 - When Θ is a discrete domain, obtain a gradient-based discrete proposal
- **Coordinatewise** factorization $q(\theta'|\theta) = \prod_{i=1}^d q_i(\theta'_i|\theta)$

$$q_i(\theta'_i|\theta) = \text{Categorical}\left(\text{Softmax}\left(\frac{1}{2} \nabla U(\theta)_i (\theta'_i - \theta_i) - \frac{(\theta'_i - \theta_i)^2}{2\alpha}\right)\right)$$

cheaply computed in parallel

Discrete Langevin Proposal (DLP)

Visualization of Discrete Langevin Proposal

$$q_i(\theta'_i|\theta) = \text{Categorical}\left(\text{Softmax}\left(\frac{1}{2}\nabla U(\theta)_i(\theta'_i - \theta_i) - \frac{(\theta'_i - \theta_i)^2}{2\alpha}\right)\right)$$

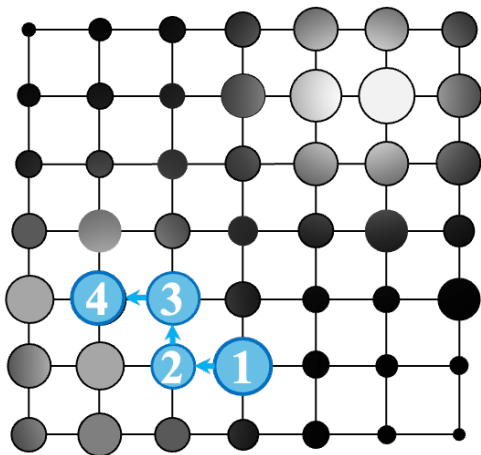


update *all* coordinates based on *gradient* info in parallel

Samplers: *discrete unadjusted Langevin algorithm* (DULA)

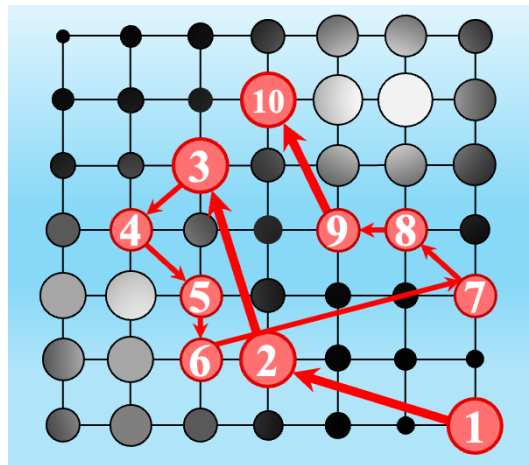
discrete Metropolis-adjusted Langevin algorithm (DMALA)

Visual Comparison



Existing discrete sampler

- Random walk
- Small move



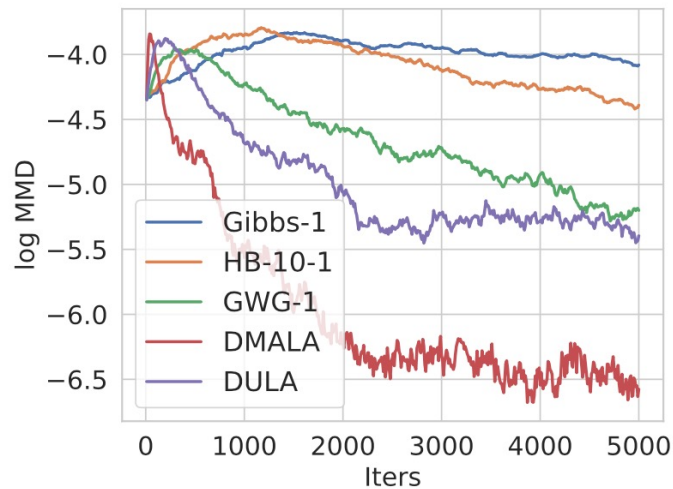
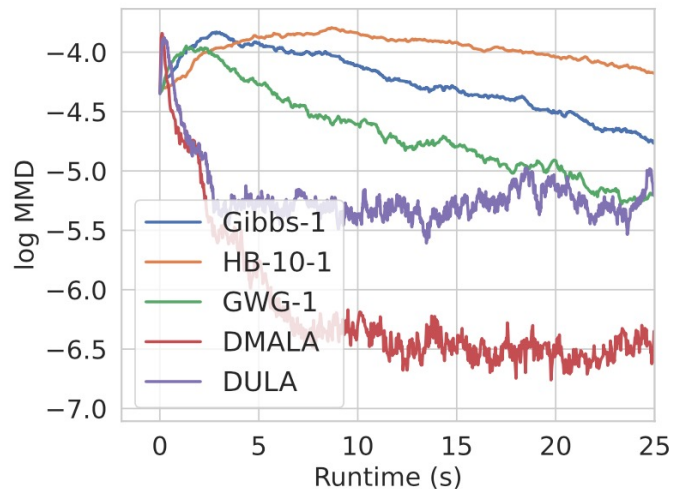
Discrete Langevin

- Gradient-informed exploration
- Large move

Convergence Analysis

Theorem (informal): *The asymptotic **bias** of DULA's stationary distribution is **zero** for **log-quadratic** distributions and is **small** for distributions that are close to being log-quadratic*

Experiments: Restricted Boltzmann Machines



- DULA and DMALA converge **faster** to the target distribution

Experiments: Deep Energy-based Models

Dataset	VAE (Conv)	EBM (Gibbs)	EBM (GWG)	EBM (DULA)	EBM (DMALA)
Static MNIST	-82.41	-117.17	-80.01	-80.71	-79.46
Dynamic MNIST	-80.40	-121.19	-80.51	-81.29	-79.54
Omniglot	-97.65	-142.06	-94.72	-145.68	-91.11
Caltech Silhouettes	-106.35	-163.50	-96.20	-100.52	-87.82

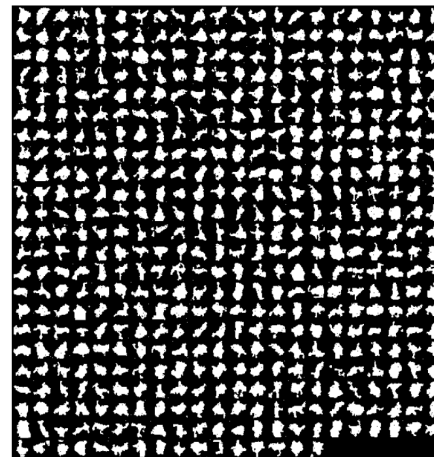
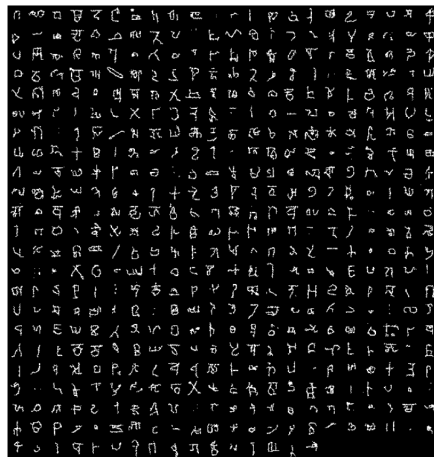
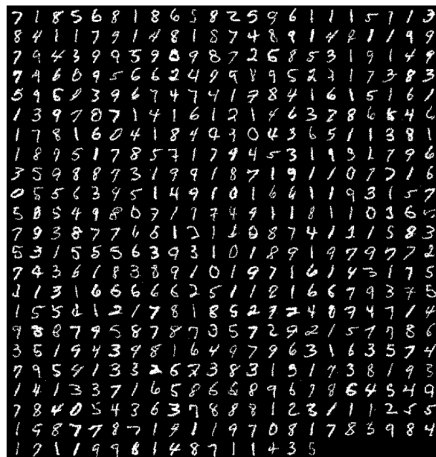


Image generation

Experiments: Language Models

Infilling Task: he had not , after all , [MASK] me the chance but [MASK] abandoned me [MASK] .

Gibbs Results:

given me the chance but had abandoned me instead
given me the chance but had abandoned me instead
given me the chance but had abandoned me instead
given me the chance but had abandoned me completely
given me the chance but had abandoned me anyway

GWG Results:

given me the chance but had abandoned me instead
given me the chance but had abandoned me himself
offered me the chance but had abandoned me completely
gave me the chance but had abandoned me anyway
given me the chance but he abandoned me instead

DMALA Results:

shown me the chance but had abandoned me anyway
shown me the chance but not abandoned me immediately
gives me the chance but also abandoned me perhaps
grants me the chance but really abandoned me entirely
offered me the chance but yet abandoned me instead

Model	Methods	Self-BLEU ($\downarrow$)	Unique n -grams (%) ($\uparrow$)						Corpus BLEU ($\uparrow$)
			Self		WT103		TBC		
			$n = 2$	$n = 3$	$n = 2$	$n = 3$	$n = 2$	$n = 3$	
Bert-Base	Gibbs	86.84	10.98	16.08	18.57	32.21	21.22	33.05	23.82
	GWG	81.97	15.12	21.79	22.76	37.59	24.72	37.98	22.84
	DULA	72.37	23.33	32.88	27.74	45.85	30.02	46.75	21.82
	DMALA	72.59	23.26	32.64	27.99	45.77	30.32	46.49	21.85
Bert-Large	Gibbs	88.78	9.31	13.74	17.78	30.50	20.48	31.23	22.57
	GWG	86.50	11.03	16.13	19.25	33.20	21.42	33.54	23.08
	DULA	77.96	17.97	26.64	23.69	41.30	26.18	42.14	21.28
	DMALA	76.27	19.83	28.48	25.38	42.94	27.87	43.77	21.73

Text infilling

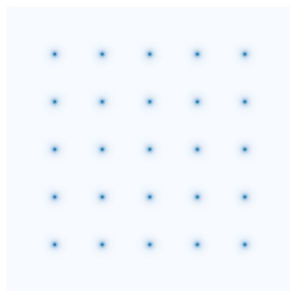
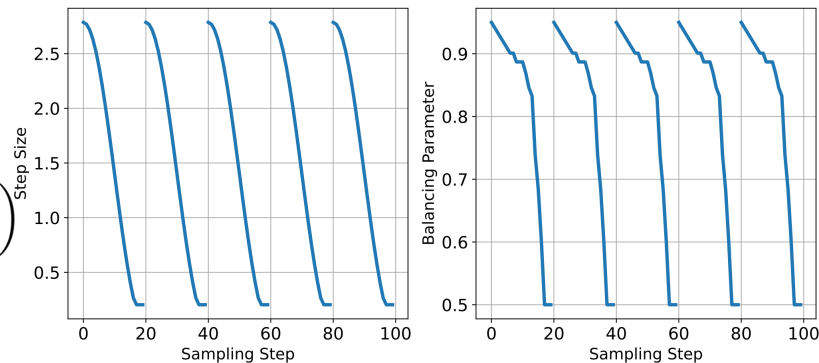


Extension: Multimodal Distributions

Cyclical stepsize and balancing parameter schedules

$$q_i(\theta'_i|\theta) = \text{Cat}\left(\text{Softmax}\left(\beta \nabla U(\theta)_i(\theta'_i - \theta_i) - \frac{(\theta'_i - \theta_i)^2}{2\alpha}\right)\right)$$

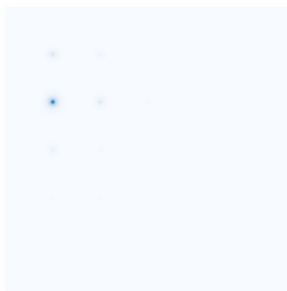
Theory: non-asymptotic convergence analysis based on TV distance



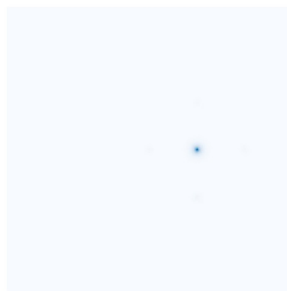
(a) Ground Truth



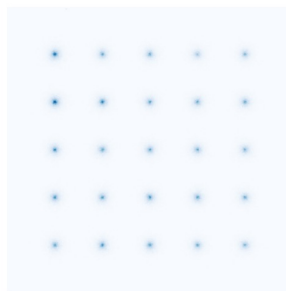
(b) Random Walk



(c) DMALA



(d) AB



(e) ACS (Ours)

Extension: Combinatorial Optimization

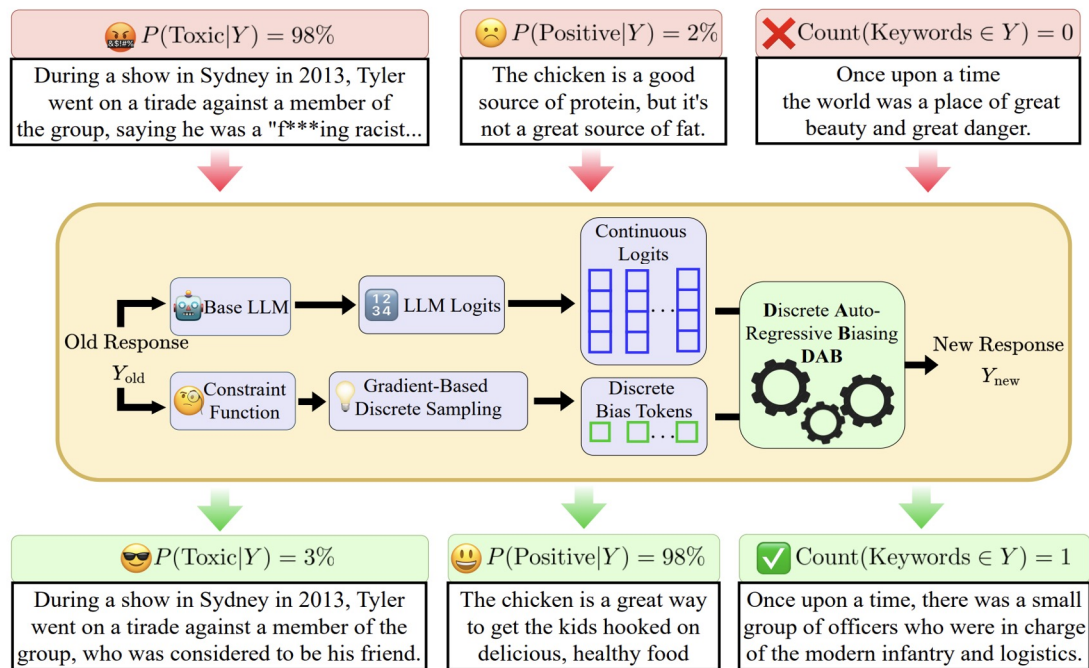
Reheat mechanism:

- Detect when to reheat
- Increase the temperature to a predefined high value

Method	Type	SATLIB		ER-[700-800]		ER-[9000-11000]	
		Size $\uparrow$	Drop $\downarrow$	Size $\uparrow$	Drop $\downarrow$	Size $\uparrow$	Drop $\downarrow$
KaMIS	OR	425.96*	-	44.87*	-	381.31*	-
Gurobi	OR	425.95	0.00%	41.38	7.78%	N/A	N/A
Intel (Li et al., 2018a)	SL+TS	N/A	N/A	38.8	13.43%	N/A	N/A
	SL+G	420.66	1.48%	34.86	22.31%	284.63	25.35%
DGL (Böther et al., 2022)	SL+TS	N/A	N/A	37.26	16.96%	N/A	N/A
LwD(Ahn et al., 2020)	RL+S	422.22	0.88%	41.17	8.25%	345.88	9.29%
DIMES(Qiu et al., 2022)	RL+G	421.24	1.11%	38.24	14.78%	320.50	15.95%
	RL+S	423.28	0.63%	42.06	6.26%	332.80	12.72%
iSCO (Sun et al., 2023b)	S-1	422.65	0.78%	43.37	3.3%	377.44	1.0%
	S-32	424.16	0.42%	45.16	-0.6%	383.50	-0.5%
ReSCO(Ours)	S-1	422.76	0.75%	44.18	1.5%	378.25	0.8%
	S-32	424.21	0.42%	45.24	-0.8%	383.75	-0.6%

Application: LLM Control Generation

- Problem: struggle to balance fluency with constraint satisfaction



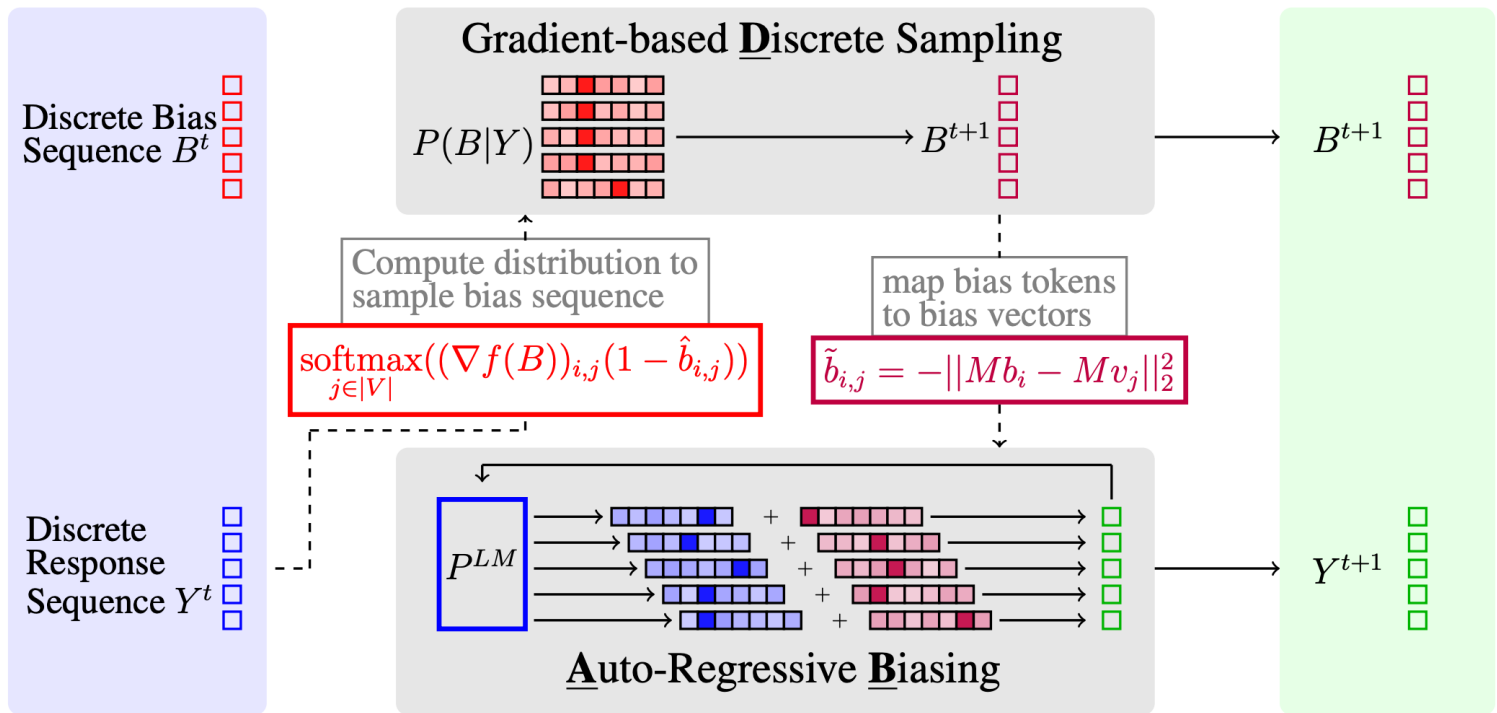
Discrete Auto-regressive Biasing (DAB)

- Our joint target distribution:

$$P(Y, B|X) \propto P^{LM}(Y|X, B) \exp(f(B|X))$$

- X: query
 - Y: response
 - f: constraint function
 - B: bias vectors
-
- How to sample?
 - Discrete Langevin within Gibbs

Discrete Auto-regressive Biasing (DAB)



DAB Results

Sentiment	Control			Fluency		
	<i>Int. Clsf</i> ↑	<i>Ext. Clsf (Yelp)</i> ↑	<i>Ext. Clsf (SST-2)</i> ↑	<i>CoLA</i> ↑	<i>REP-3gram</i> ↓	<i>PPL</i> ↓
MuCOLA	.841 ± .009	.843 ± .011	.899 ± .008	.681 ± .008	.091 ± .006	34.786 ± 2.205
COLD	.697 ± .011	.515 ± .015	.670 ± .013	.731 ± .008	.061 ± .003	15.908 ± .394
BOLT	.903 ± .006	.747 ± .013	.878 ± .001	.874 ± .005	.0008 ± .0002	9.919 ± .142
LM-Steer	-	.900 ± .008	.948 ± .006	.564 ± .008	.117 ± .007	72.153 ± 3.195
DAB (<i>Ours</i>)	.992 ± .001	.894 ± .009	.975 ± .003	.860 ± .005	.004 ± .001	11.773 ± .203

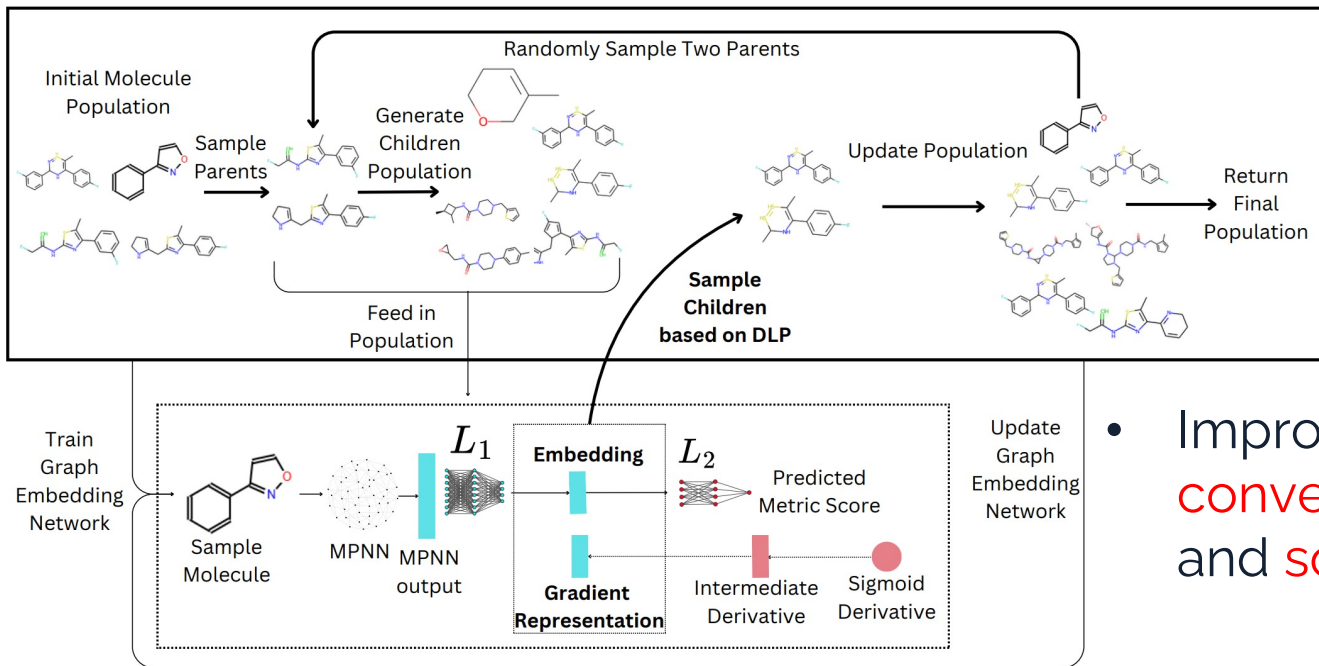
Toxicity	<i>Int. Clsf</i> ↓	<i>Avg. Max Toxicity</i> ↓	<i>Toxicity Pred. Prob.</i> ↓	<i>CoLA</i> ↑	<i>REP-3gram</i> ↓	<i>PPL</i> ↓
MuCOLA	.098 ± .002	.269 ± .006	7.6%	.691 ± .002	.006 ± .001	58.015 ± .435
COLD	.136 ± .002	.266 ± .007	10.2%	.667 ± .001	.024 ± .001	38.891 ± .177
BOLT	.065 ± .001	.264 ± .006	6.8%	.830 ± .001	.001 ± .0001	27.283 ± 2.233
LM-Steer	-	.265 ± .006	7.9%	.722 ± .002	.006 ± .002	52.697 ± .356
DAB (<i>Ours</i>)	.057 ± .001	.211 ± .006	6.8%	.806 ± .001	.001 ± .0001	25.609 ± .126

Keyword	<i>BertScore</i> ↑	<i>Success Rate</i> ↑	-	<i>CoLA</i> ↑	<i>REP-3gram</i> ↓	<i>PPL</i> ↓
MuCOLA	.8083 ± .0004	100%	-	.248 ± .004	.007 ± .001	475.301 ± 30.445
COLD	.8123 ± .0005	100%	-	.205 ± .003	.020 ± .001	241.980 ± 4.943
BOLT	.8291 ± .0003	99.1%	-	.705 ± .006	.005 ± .005	32.019 ± 1.593
DAB (<i>Ours</i>)	.8303 ± .0003	99.0%	-	.726 ± .005	.004 ± .001	23.424 ± .317

- Better fluency and constraint satisfaction trade-off
- 2x faster decoding time

Application: Molecular optimization & Drug design

- Discrete Langevin + Genetic algorithm



- Improve convergence speed and solution quality

Gradient GA: Gradient Genetic Algorithm for Drug Molecular Design
D Mukherjee, C Zhuang, Y Lu, T Fu, R Zhang. arXiv 2025

More Work on Gradient-based Discrete Sampling

- **Without** natural continuous extension

Efficient Informed Proposals for Discrete Distributions via Newton's Series Approximation
Y Xiang, D Zhu, B Lei, D Xu, R Zhang, AISTATS 2023

- **Benchmark** for discrete sampling: **7** samplers and **3** types of tasks

DISCS: A Benchmark for Discrete Sampling
K Goshvadi, H Sun, X Liu, A Nova, R Zhang, W Grathwohl, D Schuurmans, H Dai, NeurIPS 2023

- **Diffusion** language models

Coming soon!

Takeaways

- Sampling in discrete domains can be very efficient by using a **discrete version of Langevin dynamics**
- Algorithm extensions:
 - Cyclical schedules for **multimodal** distributions
 - Reheat mechanism for **combinatorial** optimization
- Applications:
 - **Classic** models: Ising, Potts, Restricted Boltzmann Machines, Energy-based models
 - **LLM** control generation
 - **Molecular** optimization & Drug design

Thank you!